

**ORIGINAL INSTRUCTIONS** 

**Instruction Manual** Step Motor Controller – CC-Link (24 VDC Servo) Series JXCM1##-#



The intended use of the step motor controller is to control the movement of an electrical actuator whilst connected to the CC-Link protocol.

### 1 Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of "Caution," "Warning" or "Danger." They are all important notes for safety and must be followed in addition

to International Standards (ISO/IEC) \*1), and other safety regulations. IEC 60204-1: Safety of machinery - Electrical equipment of machines. (Part 1: General requirements)

ISO 10218-1: Robots and robotic devices - Safety requirements for industrial robots - Part 1: Robots.

- Refer to product catalogue, Operation Manual and Handling Precautions for SMC Products for additional information.
- Keep this manual in a safe place for future reference.

<b>A</b> Caution	Caution indicates a hazard with a low level of risk which, if not avoided, could result in minor or moderate injury.
<b>▲</b> Warning	Warning indicates a hazard with a medium level of risk which, if not avoided, could result in death or serious injury.
▲ Danger	Danger indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury.

### **Marning**

- Always ensure compliance with relevant safety laws and standards.
- All work must be carried out in a safe manner by a qualified person in compliance with applicable national regulations.

### 2 Specifications

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2.1 General specifications			
Item	Specifications		
Compatible motor	Step motor (servo 24 VDC)		
Power supply voltage	24 VDC +/-10% (motor drive control, stop, lock brake release).		
Current consumption	3A (Peak 5A) maximum		
Compatible encoder	Battery-less absolute encoder (resolution: 4096 pulses / rotation)		
Serial communication	RS485		
Locking	Unlocking terminal (applicable to non-exitation magnetizing lock)		
Cable length	Actuator cable: 20 m maximum		
Cooling method	Air-cooling type		
Operating temperature	0°C to 55°C (No freezing)		
Storage temperature	-10°C to 60°C (No freezing)		
Operating humidity	90% RH or less (No condensation)		
Insulation resistance	50 M $\Omega$ (500 VDC) between the external terminals and case		
Weight	170 g (Direct mounting type) 190 g (DIN rail mounting type)		

### 2 Specifications (continued)

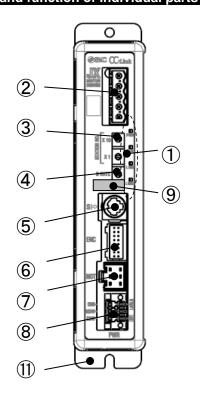
#### 2.2 CC-Link specifications

Item		Specifications				
Fieldbus		CC-Link Version 1.10				
Stati	on type	Remote device station				
	Number of stations	1 station	1 2	stations	4 sta	tions
Occupied area	Number of inputs / Number of outputs	32 points 32 points 4 words 4 words	64 / 8	points / points words / words	128 po 128 po 16 wo 16 wo	oints rds /
Com	munication speed	156 / 625 kbps, 2.5 / 5 / 10 Mbps				
Com	munication method	Broadcast Polling System				
Sync	chronization system	Frame synchronous communication				
Enco	oding method	NRZI				
Tran	smission system	Bus system (EIA RS485 compliant)				
Com	munication format	HDLC compliant				
Erro	r control system	CRC (X <sup>16</sup> +X <sup>12</sup> +X <sup>5</sup> +1)				
Setu	p file	CSP+ file (download from SMC website).				
	Applicable communication cable		CC-Link Ver.1.10-compatible cable (3-core twisted-pair cable with shield)			
Cable	Communication speed (bps)	156 k	625 k	2.5 M	5 M	10 M
Ca	Total cable length (m)	1200	900	400	160	100

### **Marning**

Special products (-X) might have specifications different from those shown in this section. Contact SMC for specific drawings.

## 3 Name and function of individual parts



### 3 Name and function of individual parts (continued)

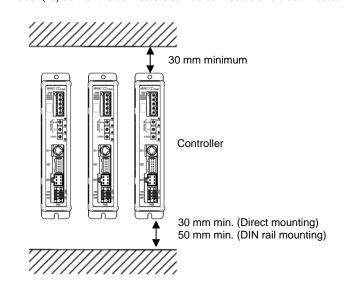
No.	Name	Description	
1	LED	LED's to indicate the controller status.	
2	Communication connector	Connect to the CC-Link communication line.	
3	STATION NO. switch	Switch for setting address (01 to 64) X1 and X10	
4	Switch for setting communication speed	Switch to set the CC-Link communication speed (B RATE).	
(5)	Serial I/O connector (8 pin) SI	Connector for the teaching box (LEC-T1) or the controller communication cable (JXC-W2A-C).	
6	Encoder connector (16 pin) ENC	Connector for actuator cable.	
7	Motor drive connector (6 pin) MOT		
8	Power supply connector (6 pin) PWR	Connector for controller power supply (24 VDC) using the power supply plug. Control power (+), Stop signal (+), Motor power (+), Lock release (+), Common power (-)	
9	Applicable electric actuator model number label	Label indicating the electric actuator part number which can be connected to the controller.	
(11)	FG	Functional Ground (When the controller is mounted, tighten screws and connect the grounding cable).	

### 4 Installation

#### 4.1 Installation

### **Marning**

- Do not install the product unless the safety instructions have been read and understood.
- Design the installation so that the temperature surrounding the controller is 55°C max. Leave enough space between the controllers so that the operating temperature of the controllers remains within the specification range.
- Mount the controller vertically with 30 mm minimum space on the top and bottom of the controller as shown below.
- Allow 60 mm minimum space between the front of the controller and a door (lid) so that the connectors can be connected and disconnected.



### 4 Installation (continued)

#### 4.2 Mounting

- The controller can be direct mounted (model JXCM17#) using screws or mounted on a DIN rail (model JXCM18#).
- When using DIN rail mounting, hook the controller on the DIN rail and press the lever down to lock it.

### **A** Caution

If the mounting surface for the controller is not flat or is uneven, excessive stress may be applied to the enclosure, which can cause failure. Be sure to mount on a flat surface.

#### 4.3 Environment

#### **⚠** Warning

- . Do not use in an environment where corrosive gases, chemicals, salt water or steam are present.
- Do not use in an explosive atmosphere.
- Do not expose to direct sunlight. Use a suitable protective cover.
- Do not install in a location subject to vibration or impact in excess of the product's specifications.
- Do not mount in a location exposed to radiant heat that would result in temperatures in excess of the product's specifications.
- Avoid mounting the controller near a vibration source, such as a large electromagnetic contactor or circuit breaker on the same panel.
- Do not use in an environment with strong magnetic fields present.

#### 4.4 Wiring

#### **A** Caution

- Do not perform wiring while the power is on.
- Confirm proper insulation of wiring.
- Do not route wires and cables together with power or high voltage
- Keep wiring as short as possible to prevent interference from electromagnetic noise and surge voltage.
- Do not use an inrush current limited type of power supply for the controller.
- Do not connect multiple wires to one connector terminal.

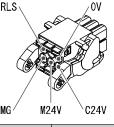
### **Power Supply Connector**

Wire the power supply cable to the power supply plug connector, then insert it into connector PWR on the controller.

- Use special screwdriver (Phoenix Contact No. SZS0.4x2.0) to open / close lever and insert the wire into the connector terminal.
- Applicable wire size: 20 AWG (0.5 mm<sup>2</sup>).

Power supply connector. SMC Part No. JXC-CPW.

Phoenix Contact Part No: DFMC1,5/3-ST-LR



Pin No.	Terminal	Function	Description
1	C24V	Power supply (+)	Positive control power.
2	M24V	Motor power (+)	Positive power for the actuator motor supplied via the controller.
3	EMG	Stop (+)	Positive power for emergency stop signal
4	0V	Common power (-)	Negative common power for M24V, C24V, EMG and LK RLS.
5	=	NC	N/A
6	LK RLS	Unlocking (+)	Positive power for lock release.

### 4 Installation (continued)

#### **Power Supply Wire specifications**

Prepare the wiring according to the following specifications (to be prepared by the user).

Item	Specifications		
Applicable wire size	<ul> <li>Single stranded wire AWG20 (0.5 mm²)</li> <li>Rated temperature of insulation should be 60°C or more.</li> <li>The OD should be Ø2.5 mm or less.</li> </ul>		
Stripped wire length	8 mm		

#### **Communication Connector**

Wire the CC-Link communication cable to the communication plug connector, then insert it into connector CN5 on the controller.

- Use special screwdriver (Phoenix Contact No. SZS0.6x3.5) to tighten the connector terminal screws. Tightening torque = 0.5 to 0.6 N•m.
- Applicable wire size: 12 to 24 AWG (0.2 to 2.5 mm<sup>2)</sup>

Straight type (LEC-CMJ-S)



T-branch type (LEC-CMJ-T)



Phoenix Contact No. MSTB2,5/5-ST-5,08 AU

Phoenix Contact No. MSTB2.5/5-ST-5.08 AU

No	Designation	Description
1	DA	CC-Link communication line A
2	DB	CC-Link communication line B
3	DG	CC-Link ground line
4	SLD	CC-Link shield
5	FG	Frame ground

- The CC-Link system has different terminating resistance requirements depending on the cables used.
- Connect a terminating resistor to both ends of the CC-Link main line.

Cable type	Resistance
CC-Link communication cable	110 Ω ±5% 1/2W
CC-Link high performance cable	130 Ω ±5% 1/2W

#### 4.5 Ground connection

• Place a ground cable with crimped terminal under one of the M4 mounting screws with a shakeproof washer and tighten the screw.

### **A** Caution

The M4 screw, cable with crimped terminal and shakeproof washer must be prepared by the user.

The controller must be connected to Ground to reduce noise. If higher noise resistance is required, ground the 0 V (signal ground). When grounding the 0 V, avoid flowing noise from ground to 0 V.

- A dedicated Ground connection must be used. Grounding should be to a D-class ground (ground resistance of 100  $\Omega$  maximum).
- The cross-sectional area of the ground cable shall be 2 mm<sup>2</sup> minimum.
- The Grounding point should be as near as possible to the controller. Keep the grounding cable as short as possible.

#### 5 Setting

#### 5.1 Switch setting

Set the CC-Link address and the CC-Link communication speed using the STATION NO, and B RATE rotary switch.



#### . STATION NO. switch

Switch name	Set range	Description
STATION NO. X10	01 to 64	Set upper bits of the station
STATION NO. X1	011004	Set lower bits of the station

The CC-Link address setting at the time of the factory shipment is set in "01".

### • B RATE (Baud Rate) switch

B RATE	Description
9	Reset of occupied number of stations *1)
85	Not used
4	10 Mbps
3	5 Mbps
2	2.5 Mbps
1	625 kbps
0	156 kbps

The CC-Link communication speed (Baud Rate) setting at the time of the factory shipment is set in "0" (156 kbps)

\*1) When the setting is 1 for the Occupied number of stations, the setting of Occupied number of stations will reset to 2 (default) by applying power with the B RATE switch set to 9.

### 6 LED Display

Refer to the table below for details of the LED status.

	LED	Description	
	OFF	Power is not supplied	
PWR	Green LED is ON	Power is supplied	
	Green LED is flashing	EEPROM memory writing	
ALM	OFF	Normal operation	
ALIVI	Red LED is ON	Controller Alarm generated	
	OFF	Normal operation	
L ERR	Red LED is ON	Francis generated	
	Red LED is flashing	Error is generated	
	OFF	CC-Link Communication disconnected	
L RUN	Green LED is ON	CC-Link Communicating	
	Green LED is flashing	Error is generated	

#### 7 How to Order

Refer to the catalogue on the SMC website (URL: https://www.smcworld.com) for the How to Order information.

#### 8 Outline Dimensions (mm)

Refer to the drawings / operation manual on the SMC website (URL: https://www.smcworld.com) for outline dimensions.

#### 9 Maintenance

#### 9.1 General Maintenance

### **⚠** Caution

- Not following proper maintenance procedures could cause the product to malfunction and lead to equipment damage.
- Before performing maintenance, turn off the power supply. Check the voltage with a tester 5 minutes after the power supply is turned OFF.
- If any electrical connections are disturbed during maintenance, ensure they are reconnected correctly and safety checks are carried out as required to ensure continued compliance with applicable national regulations.
- Do not make any modification to the product.
- Do not disassemble the product, unless required by installation or maintenance instructions.

#### ⚠ Caution

- Maintenance should be performed according to the procedure indicated in the Operation Manual.
- When equipment is serviced, first confirm that measures are in place to prevent dropping of work pieces and run-away of equipment, etc, then cut the power supply to the system. When machinery is restarted, check that operation is normal with actuators in the correct position.

### **Marning**

- · Perform maintenance checks periodically.
- · Confirm wiring and screws are not loose. Loose screws or wires may cause unexpected malfunction.
- · Conduct an appropriate functional inspection and test after completing maintenance. In case of any abnormalities (if the actuator does not move, etc.), stop the operation of the system. Otherwise, an unexpected malfunction may occur and it will become impossible to ensure safety. Operate an emergency stop instruction to confirm safety.
- Do not put anything conductive or flammable inside of the controller.
- Ensure sufficient space around the controller for maintenance.

### 10 Limitations of Use

10.1 Limited warranty and Disclaimer/Compliance Requirements Refer to Handling Precautions for SMC Products.

### 11 Product disposal

This product shall not be disposed of as municipal waste. Check your local regulations and guidelines to dispose of this product correctly, in order to reduce the impact on human health and the environment.

### 12 Contacts

Refer to www.smcworld.com or www.smc.eu for your local distributor /

# **SMC** Corporation

URL: <a href="https://www.smcworld.com">https://www.smc.eu</a> (Europe) SMC Corporation, 4-14-1, Sotokanda, Chiyoda-ku, Tokyo 101-0021, Japan Specifications are subject to change without prior notice from the manufacturer. © 2021 SMC Corporation All Rights Reserved. Template DKP50047-F-085M